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Computational algorithm for the verification of reinforced concrete sections in fire situation

Algoritmo computacional para verificação de seções de concreto armado em situação de incêndio







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Abstract

Reinforced concrete structures may have reduced strength due to the degradation of their mechanical properties by temperature. This can increase the risk of structural collapses. Thus, the structural design should consider its behavior at room temperature and in fire situation (ABNT NBR 14432:2001). This study presents the development of an algorithm to verify the strength of any reinforced concrete sections subjected to unsymmetrical bending at room temperature and in fire situation. For this purpose, a stress integration algorithm was implemented from the strain profile of the section according to ABNT NBR 15200:2012, linked to a finite element mesh generator and a thermal analysis algorithm. For validation of the developed program, called Pisafo, the results obtained were compared with those in the technical literature: obtained in experiments (with differences of up to 28.5%) and with recognized software solutions (with differences of up to -14.8%). The largest variations in relation to the experiments used by the program and the non-consideration of spalling in the computational analysis.

Keywords: reinforced concrete, fire, design, unsymmetrical bending, computational algorithm.

Resumo

As estruturas de concreto armado podem ter sua capacidade resistente reduzida devido à degradação de suas propriedades mecânicas com a temperatura, aumentando o risco de colapsos estruturais. Assim, o dimensionamento de uma estrutura deve considerar seu comportamento em temperatura ambiente e em situação de incêndio (ABNT NBR 14432:2001). Neste trabalho, apresenta-se o desenvolvimento de um algoritmo para verificação da resistência de seções quaisquer de concreto armado à flexão composta oblíqua em temperatura ambiente e em incêndio. Para isso, implementou-se um algoritmo integrador de tensões a partir do perfil de deformações da seção segundo a ABNT NBR 15200:2012, vinculado com um gerador de malhas de elementos finitos e com um algoritmo análise térmica. Na validação do programa desenvolvido, denominado Pisafo, compararam-se os resultados obtidos com os apresentados na literatura: obtidos em experimentos, com diferenças de até 28,5%, e com programas consagrados, com diferenças de até -14,8%. As maiores variações em relação aos experimentos podem ser atribuídas às diferenças entre as propriedades térmicas do concreto nos experimentos com as prescritas em normas utilizadas no programa e à não consideração do *spalling* na análise computacional.

Palavras-chave: concreto armado, incêndio, verificação, flexão composta oblíqua, algoritmo computacional.

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1. Introduction

According to Brushlinsky *et al.* [1], in 2014, in 23 countries surveyed, there were recorded a total of 819,265 fires in buildings, involving thousands of people injured and killed, as well as a financial loss of millions of dollars caused by the fires.

To avoid further material losses and especially lives, research in the field of fire has intensified more and more. Experiments with the goal of investigating the behavior of reinforced concrete elements subjected to high temperatures [2, 3, 4, 5], researches for the analysis of thermal and thermomechanical problems of structures [6, 7, 8, 9], studies that have investigated and provided simplified [10, 11, 12, 13, 14] and alternative [15, 16, 17] methods for design and verification of reinforced concrete elements have been performed in recent times.

Studies on design up to that time were limited to analyzing rectangular sections of reinforced concrete in fire situation, comprising only normal composite bending. Therefore, there is a deficiency in the general treatment of composite bending (normal and unsymmetrical) for its application in other sections, such as T, L and circular sections, widely used today as columns in tall buildings.

In order to evaluate a structure in fire situation, it is necessary first to understand the fire phases, compartment geometry, type of combustible material, type of masonry coating and degree of ventilation, according to Silva [18]. Only then it is possible to select a fire curve [19, 20, 21, 22] suitable for the good simulation of the reinforced concrete structure.

The main advantage of reinforced concrete is that many buildings with this type of structure that suffered serious fires could be restored and put back into use [23], such as the Santos Dumont airport building in Rio de Janeiro - Brazil [24]. Due to a slow heat transfer, the internal region of the cross-sections of reinforced concrete does not reach the high temperatures of the faces exposed to fire, remaining with lower temperatures and, therefore, greater mechanical strength [25]. This characteristic provides a good degree of rehabilitation to concrete structures.

In relation to the decay of mechanical properties of the concrete with the temperature, this can be attributed to the physical-chemical changes in the cement paste and in the aggregates, and to the difference in the thermal deformations between these [26]. In this way, the greater problems caused in the reinforced concrete structure occur at temperatures in the range of 500 °C to 600 °C [27]. It is within this range that the steel of the reinforcement rapidly loses its tensile strength.

An important phenomenon that occurs in structural elements of reinforced concrete in fire situation is the spalling, which causes loss of the resistant area due to the concrete disintegration [28]. Spalling can be manifested as pop-out, from an aggregate, due to the differential thermal deformations between the aggregate and the concrete matrix (Figure 1.a); as sloughing as shown in Figure 1.b; or as explosive spalling, Figure 1.c.

There are several reasons that influence the occurrence of spalling: moisture content, porosity and permeability of concrete, stress conditions, type of aggregate used in concrete, section of the element, concrete cover used and rate of heating [29, 30]. Each factor mentioned has its peculiarities and can act increasing or decreasing the probability of occurrence of this phenomenon in the concrete.

Some researchers have already observed that the moisture content has a great influence on the internal temperature of the concrete elements, besides directly interfering with the pore-pressure developed during the heating process [31]. Deeny *et al.* [32] emphasize the importance of the implementing fully coupled hygrothermo-mechanical models for an accurate evaluation of spalling, but highlight the great variability that the numerical results can present in relation to experimental data.

Thus, by knowing the effects of fire, it is necessary to consider the changes in the thermal and mechanical properties of concrete and steel due to the temperature increase in these materials. The thermal properties required for thermal analysis of the materials composing the reinforced concrete are the specific mass, influenced by the water loss of the concrete matrix and by the volume variation due to material expansion, specific heat and thermal conductivity [29]. With respect to the main mechanical properties of the materials composing the reinforced concrete, it can be mentioned the modulus of elasticity, the tensile and compressive strength and the stress-strain relationships [29].

In this context, there are no studies on the development of an algorithm for the verification of the strength of any sections of reinforced concrete when subjected to unsymmetrical bending. Thus, this study aimed to present a computational algorithm capable of



(a) Pop-out

Figure 1 Types of spalling in concrete Source: www.google.com

(b) Sloughing



numerically simulating, in 2D, the temperature distribution in reinforced concrete sections in fire situation, following any fire curve (temperature × time), and to verify its resistance subjected to unsymmetrical bending. In addition, with this algorithm it is possible to construct the $M_y \times M_x$, $M_x \times N$ and $M_y \times N$ interaction diagrams of concrete cross-sections for various fire exposure times.

Importantly, the algorithm shown in this research encloses an alternative method of design, not considering the influence of spalling and thermal deformations of the materials on the strength capacity of the elements evaluated.

2. Material and methods

The computational algorithm developed in this study, called *Pisafo*, corresponds to the mechanical analysis, a stress integration from the cross-section strain profile, directly coupled to a finite element mesh generator and to a thermal analysis algorithm. Each of these modules is described in the following items.

2.1 Mesh generation

To generate the finite element mesh, *Pisafo* uses the algorithm of the *EasyMesh* mesh generator [33], with its converted code from C++ (its default language) to Delphi, by Bitencourt [34].

EasyMesh is a freeware two-dimensional mesh generator for three-node linear triangular elements developed at MIT. It allows to generate an unstructured mesh with or without holes, and it is also possible to perform a localized refinement or coarsening of the mesh.

EasyMesh uses the Delaunay triangulation, the Laplace smoothing, and has a relaxation method to avoid creating nodes surrounded by more than 7 and less than 5 elements.

2.2 Thermal analysis

For thermal analysis, *Pisafo* uses the thermal analysis algorithm of *Thersys*, also developed in Delphi by Ribeiro [7]. This algorithm performs transient and nonlinear thermal analysis for two-dimensional and three-dimensional elements of any geometry, considering several fire curves and the thermal properties of the materials. The temperature of the structural elements is determined by the differential heat transfer formulation adapted to the Finite Element Method, based on a fire curve and dependent on the boundary conditions.

2.2.1 Mechanisms of heat transfer

For the simulation of a fire, there is a combined action of the three mechanisms of heat transfer: conduction (in the domain), convection and radiation (in the boundary).

a) Conduction

In conduction, energy is propagated through molecular agitation within a body or environment (solid, liquid or gaseous), or between different bodies in physical contact. The heat transfer by conduction is given by the Fourier law according to Equation (1):

$$\lambda \nabla^2 \theta + Q = \rho c \frac{\partial \theta}{\partial t} \tag{1}$$

where λ is the thermal conductivity of the material (W/(m°C)), ∇ is the differential operator (gradient), θ is the material temperature (°C), Q is the heat flux generated inside the material (W/m³), ρ is the specific mass of the material (kg/m³), *c* is the specific heat of the material (J/(kg°C)), *t* is the time (s) and $\partial \theta / \partial t$ is the temperature gradient in time.

b) Convection

Convection is a mechanism of heat transfer through the movement of a fluid or between it and solid surfaces (where the fluid corresponds to the heated gases and the solid is the structural element). When convection currents form due to the difference in density (and temperature) between masses of gases, natural convection occurs. If these currents are caused by external reasons, forced convection is considered.

The convection heat flux is determined by Newton's law of cooling, according to Equation (2):

$$q = \alpha_c (\theta_s - \theta_f) \tag{2}$$

where *q* is the convective heat flux emitted by the surface per unit area (W/m²), α_c is the coefficient of heat transmission by convection (W/(m² °C)), θ_s is the surface temperature of the solid (°C) and θ_t is the average temperature of the fluid (°C).

c) Radiation

The transfer of heat by radiation occurs through the propagation of electromagnetic waves due to the diffusion of the flames. As these waves can propagate in a vacuum, unlike conduction and convection, no contact between bodies is required. In addition, heat transmission through radiation has its maximum efficiency in the vacuum [8]. The maximum flow of radiant heat that can be emitted by the surface is calculated by Equation (3) developed by an experiment carried out by Josef Stefan in 1879 and, analytically, by Ludwig Boltzmann in 1884, called the Stefan-Boltzmann law:

$$q = \varepsilon_{res} \sigma \left(\theta_s^4 - \theta_f^4 \right) \tag{3}$$

where *q* is the net heat flux emitted by radiation (W/m²), ε_{res} is the resultant emissivity of the heated surface, σ is the Stefan-Boltzmann constant of proportionality equal to 5.6697 × 10⁻⁸ (W/ (m²K⁴)), θ_s is the absolute surface temperature of the solid (Kelvin) and θ_r is the average absolute temperature of the fluid (Kelvin).

Thersys allows several boundary conditions, of which *Pisafo* inherits basically two types, combining convection and radiation, according to Equation (4):

- surfaces with cooling, where θ_f is the room temperature;
- fire surfaces, where θ_t is the temperature of hot gases.

$$q = -\lambda \frac{\partial \theta}{\partial n} = \alpha_c (\theta_s - \theta_f) + \varepsilon_{res} \sigma (\theta_s^4 - \theta_f^4) = \alpha (\theta_s - \theta_f) \quad \text{in } \Gamma_q \qquad (4)$$

where $\partial \theta / \partial n$ is the surface temperature gradient and α is the convective-radiative coefficient.

In addition to these cases, the boundary condition in which the surface is isolated (adiabatic) is also possible. In this way, there is no heat transfer between the structure and the gases.

2.2.2 Structure of Thersys

The program *Thersys* was elaborated using the concept "object oriented" with the aim of facilitating maintenance and additions in



Figure 2

Structure of the program Thersys in classes [7]

the code [7]. The structure of the program can be seen in Figure 2. The program *Pisafo* inherits from *Thersys* the classes TFEShape, TThermic and TSKYMatrix, that allow to perform the thermal analysis. The TSpline class acts as a secondary class to manage interpolation of user-supplied data in the form of tables.

The class TFEShape manages the class TFETriangle that contains the Gaussian quadrature tables, calculates the Jacobian and the Cartesian derivatives. It also has the form functions and the local derivatives (class TT3) for the finite element generated by the *EasyMesh* algorithm.

The class TSkyMatrix solves the system of equations. It manages the stiffness matrix and makes the call available to the TSkyLDU (Cholesky factorization) solution algorithm.

The class TThermic manages the data and the coefficients of the thermal problem, calculates all the thermal matrices, vectors of nodal flows and performs thermal analysis using an iterative and incremental algorithm [7].

2.3 Mechanical analysis

The stress/strain profile integration algorithm for obtaining the interaction diagrams of concrete cross-sections comprises the following steps:

a) center of gravity of the cross section.

The total area of the cross section and the static moments of area around the *x* and *y* axes can be obtained by Gaussian quadrature according to Equations (5), (6) and (7), respectively. The coordinates of the center of gravity are given by Equations (8) and (9):

$$A_{t} = \sum_{e=1}^{netem} \sum_{p=1}^{npg} |J| w$$

$$Q_{x} = \sum_{e=1}^{netem} \sum_{p=1}^{npg} y_{p} |J| w$$
(5)
(6)

$$Q_{y} = \sum_{e=1}^{nelem} \sum_{p=1}^{npg} x_{p} |J| w$$
(7)

$$x_g = Q_y / A_t \tag{8}$$

$$y_g = Q_x / A_t \tag{9}$$

where A_t is the total area of the section, *nelem* is the number of elements in the mesh, *npg* is the number of Gauss points in the element, |J| is the determinant of the Jacobian matrix at the Gauss point, *w* is the weight of the Gauss point in the quadrature, Q_x is the static moment of area around the *x*-axis, y_p is the coordinate *y* of the Gauss point, Q_y is the static moment of area around the *y*-axis, x_p is the coordinate *x* of the Gauss point, x_g and y_g are the coordinates of the center of gravity.

b) distances for the calculation of the strain profile

The distances for calculating the strain profile are illustrated in Figure 3. Given the angle (β) that the neutral line makes with the *x*-axis, it is necessary to identify the highly compressed edge of the concrete section farthest from the center of gravity (x_{cc}), the tensioned edge of the concrete section farthest from the center of gravity (x_{ct}) and the tensile reinforcement bar farthest from the center of gravity (x_{n}).

In order to calculate these distances, one must first obtain the coordinates (x_{β} and y_{β}) of the unit vector perpendicular to the neutral line (*NL*), according to Equations (10) and (11):

$$x_{\beta} = \cos(\beta + 90^{\circ}) \tag{10}$$

$$y_{\beta} = \operatorname{sen}(\beta + 90^{\circ}) \tag{11}$$

The calculation of distances is done by projecting the position vector (with origin at the center of gravity) of each edge of the crosssection and the reinforcements in the direction of the unit vector perpendicular to the neutral line, according to Equation (12):

$$d_i = (x_i - x_g) x_\beta + (y_i - y_g) y_\beta$$
(12)



Figure 3

Distances in a section considering the neutral line at an β angle to the x-axis



Figure 4

Domains of strain at the ultimate limit-state according to ABNT NBR 6118:2014 [35]

where x_i and y_i are the coordinates of the point under analysis and d_i is the distance from that point to the center of gravity (*G*), measured perpendicular to the neutral line.

c) strain limits for concrete (ε_c) and reinforcement (ε_t)

After determining the maximum steel strain ($\varepsilon_{yd,max}$) according to the steel type and its temperature [35, 36], the strains ε_c and ε_r , shown in Figure 3, are calculated. These strains are obtained in function of the variable δ , from the definition of the strain domains at the ultimate limit state (Figure 4) and their fractions, according to Equation (13).

$$\delta = \begin{cases} 0 & \rightarrow \quad \text{line a} \\ 0 < \delta \le 10 & \rightarrow \quad \text{domain 1} \\ 10 < \delta \le 20 & \rightarrow \quad \text{domain 2} \\ 20 < \delta \le 30 & \rightarrow \quad \text{domain 3} \\ 30 < \delta \le 40 & \rightarrow \quad \text{domain 4} \\ 40 < \delta \le 50 & \rightarrow \quad \text{domain 4a} \\ 50 < \delta < 60 & \rightarrow \quad \text{domain 5} \\ 60 & \rightarrow \quad \text{line b} \end{cases}$$
(13)

d) strain at Gauss points in the finite element mesh

The strain at a Gauss point of the mesh can be obtained by the Strain Compatibility Method, considering a similarity of triangles based on the strains of the regions defined by the coordinates x_{cc} (ε_c) and x_{tr} (ε_t), according to Equation (14) and Figure 3:

$$\varepsilon(d_{i}) = \frac{\varepsilon_{c} (x_{tt} + d_{i})}{x_{cc} + x_{tt}} + \frac{\varepsilon_{t} (x_{cc} - d_{i})}{x_{cc} + x_{tt}}$$
(14)

where d_i is the distance from the Gauss point to the center of gravity of the section, measured perpendicular to the neutral line, and obtained as a function of its coordinates (x_i , y_i) from Equation (12). e) stress at Gauss points

The calculation of the stress at each Gauss point of the mesh from

Table 1

Parameters for the parabola-rectangle diagram of ABNT NBR 6118:2014 [35] according to the concrete class

Parameters	< C50	C50 to C90
ε _{c2} (‰)	2.0	2.0 + 0.085 (f _{ck} - 50) ^{0.53}
ε _{cu} (‰)	3.5	2.6 + 35 ((90 - f _{ck})/100) ⁴
n	2.0	1.4 + 23.4 ((90 - f _{ck})/100) ⁴

the strain profile is performed considering the parabola-rectangle diagram presented by ABNT NBR 6118:2014 [35] or the diagram indicated by ABNT NBR 15200:2012 [36], and for the reinforcement, the simplified diagram presented by Moreira *et al.* [17] or the diagram indicated by ABNT NBR 15200:2012 [36].

The stress-strain diagram of the concrete at high temperatures is obtained by the third-order Popovics equation indicated by ABNT NBR 15200:2012 [36] and by EN 1992-1-2:2004 [29], according to Equation (15).

$$\sigma_{c,\theta} = f_{ck} k_{c,\theta} \frac{3 \left(\frac{\varepsilon_{c,\theta}}{\varepsilon_{c1,\theta}}\right)}{2 + \left(\frac{\varepsilon_{c,\theta}}{\varepsilon_{c1,\theta}}\right)^3}$$
(15)

where $\sigma_{c,\theta}$ is the compressive stress value of the concrete at high temperature, f_{ck} is the characteristic strength of concrete at room temperature, $k_{c,\theta}$ is the concrete strength reduction coefficient for high temperatures [36], $\varepsilon_{c,\theta}$ is the specific linear strain of concrete at high temperature, Equation (14), and $\varepsilon_{c1,\theta}$ is the specific linear strain corresponding to the maximum compressive strength of the concrete at high temperature [36].

Alternatively to the diagram proposed by ABNT NBR 15200:2012 [36], according to previous studies conducted by Albuquerque *et al.* [15] and Moreira *et al.* [17] with satisfactory results, it can be used the parabola-rectangle diagram of ABNT NBR 6118:2014 [35], considering the strength of concrete adapted to high temperatures, as follows:

$$\sigma_{c,\theta} = \begin{cases} f_{ck} \ k_{c,\theta} \left[1 - \left(1 - \frac{\varepsilon_c}{\varepsilon_{c2}} \right)^n \right], & \text{for } 0 \le \varepsilon_c < \varepsilon_{c2} \\ f_{ck} \ k_{c,\theta}, & \text{for } \varepsilon_{c2} \le \varepsilon_c \le \varepsilon_{cu} \end{cases}$$
(16)

in which ε_{c2} is the specific compressive strain of the concrete at reaching the maximum strength, and ε_{cu} is the ultimate compressive strain (rupture), both indicated in Table 1.

reinforcement (steel)

The stress-strain diagrams of the passive reinforcement bars at high temperatures can be elaborated from the equations indicated by ABNT NBR 15200:2012 [36].

Alternatively, it can be used the simplified diagram proposed in ABNT NBR 6118:2014 [35], with the expressions also adapted for high temperatures. Although this diagram is valid only for the temperature range between -20°C and 150°C, in previous studies by Soares [12], Castro [37] and Moreira *et al.* [17] this diagram was used to calculate structures in fire situation and the results were satisfactory.

For this diagram, the steel yield strain at high temperatures is given by:

$$\varepsilon_{yd,\theta} = \frac{f_y \, \kappa_{s,\theta}}{E_s \, \kappa_{E_s,\theta}} \tag{17}$$

and the stress in the reinforcement bars at high temperatures can be obtained by:

$$\sigma_{s,\theta} = \begin{cases} E_s \, k_{Es,\theta} \, \varepsilon_s, & \text{for } \varepsilon_s < \varepsilon_{yd,\theta} \\ f_y \, k_{s,\theta}, & \text{for } \varepsilon_s \ge \varepsilon_{yd,\theta} \end{cases}$$
(18)

where f_y is the steel tensile strength of the passive reinforcement at room temperature, E_s is the modulus of elasticity of the steel at room temperature, $k_{s,\theta}$ and $k_{Es,\theta}$ are the factors of reduction of tensile strength and the modulus of elasticity of steel at high temperatures,



Figure 5



respectively, indicated in ABNT NBR 15200:2012 [36], ε_{s} is the specific strain of the reinforcement and σ_{s} is the normal stress in the steel at high temperatures.

f) calculation of the design strength (axial load and bending moments)

With the stresses determined at each Gauss point, it can be calculated the cross-section design strength to axial load (N_{Rd}) and the bending moments ($M_{x,Rd}$ and $M_{y,Rd}$) using a Gaussian quadrature integration, according to Equations (19), (20) and (21):

$$N_{Rd} = \sum_{e=1}^{hetem} \sum_{p=1}^{hpg} \sigma_{e,p} |J| w$$
(19)

$$M_{x,Rd} = \sum_{e=1}^{nelem} \sum_{p=1}^{npg} \sigma_{e,p} \left(y_{e,p} - y_g \right) |J| w$$
(20)

$$M_{y,Rd} = -\sum_{e=1}^{nelem} \sum_{p=1}^{npg} \sigma_{e,p} \left(x_{e,p} - x_g \right) |J| w$$
⁽²¹⁾

where $\sigma_{e,p}$ is the stress at a Gauss point (*p*) of a given element (*e*) with coordinates ($x_{e,p}$, $y_{e,p}$) and the other parameters have already been defined.

2.4 Computational implementation

The computer program developed in this study, called *Pisafo*, was implemented in the Delphi development environment, using the Object Pascal language, in compatibility with the algorithms of the mesh generator [34] and *Thersys* [7].

Based on the finite element mesh and the temperatures obtained in the thermal analysis, *Pisafo* integrates the stresses in the reinforced concrete cross-section in order to obtain the design strength, considering the variables δ and β . Thus, an algorithm that allows to vary δ and β has been implemented in order to obtain the interaction diagrams:

- $\blacksquare M_{v} \times M_{x}, \text{ for a set value of } N;$
- $M_{x} \times N$, for a set value of M_{y} ; and
- $M_v \times N, \text{ for a set value of } M_{x}.$

3. Results and discussion

Examples of application were made with the objective of validating the program *Pisafo*. The results of the maximum axial load supported by columns of different sections were compared with those presented in the technical literature, obtained in experiments. The results of the maximum bending moment supported by beams, in order to validate the calculations of the bending moments, and the $M_y \times M_x$ interaction diagrams were also compared with the technical literature, obtained with the use of recognized programs.

3.1 Experiments of Xu and Wu [2]

Two columns with "+" and "T" section were analyzed, following the same conditions of the experiments performed by Xu and Wu [2]. The tests consisted of applying a centrally compression axial load to the column, which remained constant during exposure to fire, until rupture of the structural element.

The standard fire curve of ISO 834-1:1999 [21] was used for fire simulation. The columns had 12 longitudinal bars with 16 mm diameter and a yield strength of 418 MPa. In *Pisafo*, concrete with silica aggregate, moisture content of 2% and concrete cover of 30 mm were considered, highlighting that the authors [2] did not specify the concrete cover used. The ultimate strength experiments of the columns were performed between 150 and 180 days after concreting, and they were calculated to have an average compressive strength of approximately 25 MPa.

With respect to the boundary conditions, the columns under analysis have all their faces exposed to fire. The dimensions of the columns studied are shown in Figure 5.

a) "+" section

The column had a cubic strength f_{cu} of 37.6 MPa after 150 days of concreting, equivalent to a cylindrical strength f_{ck} [38] of 30.38 MPa.



Figure 6

Interaction diagrams of bending moments and axial load using diagrams proposed by ABNT NBR 15200:2012: (a) $M_{y,Rd} \times M_{x,Rd'}$ (b) $M_{x,Rd} \times N_{Rd}$ and (c) $M_{y,Rd} \times N_{Rd}$ (room temperature: thick line; 245 minutes of fire: thin line)

In the experiment, the column was subjected to a compression axial load of 1480 kN. It supported 245 minutes until it collapse.

With *Pisafo*, it was possible to obtain the largest compression axial load supported by the cross section of the column, besides the in-



Figure 7

Position of the thermocouples in the "+" section (size in millimeters) [2]

teraction diagram of bending moments and axial load for the room temperature and in fire situation (Figure 6).

In order to obtain cross-section temperatures during the test, the authors installed thermocouples at four points in the section, as shown in Figure 7. Thus, it was possible to compare the temperatures calculated by *Pisafo* with the temperatures measured and calculated by Xu and Wu [2], according to Figure 8. There was a good agreement between the experimental results and those obtained by *Pisafo*.

b) "T" section

The column showed a cubic strength f_{cu} of 34.8 MPa after 150 days of concreting, corresponding to a cylindrical strength f_{ck} [38] of 28.43 MPa. In the experiment, the column was subjected to a compression axial load of 1902 kN. It supported 148 minutes of fire until collapse.

Table 2 lists the results obtained by *Pisafo* using the diagrams proposed in ABNT NBR 6118:2014 [35] modified for high temperatures and the diagrams proposed in ABNT NBR 15200:2012 [36], with their respective errors in relation to experimental results obtained by Xu and Wu [2]. In the numerical analyses, the seeds for mesh generation were 20 mm for the concrete elements and 8 mm for the steel elements.

The use of the diagrams proposed in ABNT NBR 6118:2014 modified for high temperatures tends to overestimate the strength capacity of the structural element, while the use of the diagrams proposed in ABNT NBR 15200:2012 leads to results closer to those



Figure 8 Temperatures obtained at "+" section

Table 2

Axial load strength (kN) of "+" and "T" sections

Section	Xu and Wu [2] —	Diagrams of NBR 6118 [35]		Diagrams of NBR 15200 [36]	
		Pisafo	Error	Pisafo	Error
+	-1480	-1721.77	16.3 %	-1363.45	-7.9 %
Т	-1902	-2444.04	28.5 %	-1992.39	4.8 %



Figure 9

Sizes of the beams (in millimeters) with (a) negative and (b) positive reinforcement

obtained in experiments. In general, the results obtained by *Pisafo* proved to be satisfactory when compared with the experimental results of Xu and Wu [2].

3.2 Super TempCalc

The experiments performed by Xu and Wu [2] restricted any rotation and horizontal displacement at the ends of the columns, allowing only vertical displacement. With this, it became necessary to validate the calculation of the bending moment strength by means of the analysis of beams.

For this, the Swedish computer program Super TempCalc, developed by Fire Safety Design [39] was used. The analyses considered the standard fire curve of ISO 834-1:1999 [21], concrete with silica aggregate, with a compressive strength of 25 MPa and a moisture content of 1.5 %. The reinforcement bars were of steel with yield strength of 500 MPa.

It was considered that three faces of the beam (lateral and inferior) were exposed to the fire, being the superior face defined as adiabatic. The sizes of the beams with positive reinforcement and negative reinforcement are shown in Figure 9.

a) beam with negative reinforcement

The reinforced beam considered had 3 bars of 10 mm and with concrete cover of 25 mm. The fire time for thermal analysis was 60 minutes. As occurred for columns, a smaller size of the elements in the concrete and steel mesh results in a higher strength of the structure. However, with that consideration, the time spent for thermal analysis also becomes longer.

Table 3 lists the results obtained by *Pisafo* using the diagrams proposed in ABNT NBR 6118:2014 [35] modified for high temperatures and the diagrams proposed by ABNT NBR 15200:2012 [36], with the respective errors in relation to the result obtained by Super TempCalc [39]. In this table, the seed used for the mesh generator in case A: 15 mm for concrete elements and 6 mm for steel elements, and in case B: 10 mm for concrete elements and 4 mm for steel elements.

b) beam with positive reinforcement

For the case of positive reinforcement, the reinforced beam adopted had 2 bars of 25 mm and concrete cover of 40 mm. The fire time for the thermal analysis was 120 minutes.

Table 4 presents the results obtained by *Pisafo* in comparison to the result obtained by Super TempCalc, with the same considerations of the meshes and of the stress-strain diagrams of the materials made in the previous subitem.

In the case of cross-sections subjected to bending, the results obtained by *Pisafo* were accurate for situation of negative bending moment and relatively conservative for situation of positive bending moment. In this case, the diagrams used [35, 36] had less interference in the results obtained.

3.3 $M_{\nu} \times M_{\chi}$ interaction diagram at room temperature

Also for validation of *Pisafo*, the comparison was made between a $M_y \times M_x$ interaction diagram generated by *Pisafo* and the same diagram obtained, at room temperature, by the web application developed at USP (http://www.lmc.ep.usp.br/pesquisas/TecEdu/). The cross-section of reinforced concrete considered in this validation has 20 × 20 cm², consisting of concrete with f_{ck} of 25 MPa and 4 steel bars of CA50 with a diameter of 10 mm and with 25 mm of concrete cover. The fire analysis used the standard fire curve

Table 3

Bending moment strength (kN.cm) of the beam with negative reinforcement

Super TempCalc [39]	Case	Diagrams of NBR 6118 [35]		Diagrams of NBR 15200 [36]	
		Pisafo	Error	Pisafo	Error
3742.12	А	3722.70	-0.52 %	3618.61	-3.30 %
	В	3726.14	-0.43 %	3624.67	-3.14 %

Table 4

Bending moment strength (kN.cm) of the beam with positive reinforcement

Super TempCalc [39]	Case	Diagrams of NBR 6118 [35]		Diagrams of NBR 15200 [36]	
		Pisafo	Error	Pisafo	Error
13826.66	А	11888.87	-14.0 %	11773.64	-14.8 %
	В	11928.78	-13.7 %	11812.43	-14.6 %

of ISO 834-1:1999 [21], 0 % moisture content for concrete and all faces exposed to fire (Figure 10). The cross section was also subjected to an axial load of 420 kN.

For validation of calculations of the column in fire situation, a TRRF of 0.1 minute was set. In this way, the section does not reach a high temperature and, with this, there is no reduction in mechanical properties. When considering factors for actions and strength in fire situation identical to those used at room temperature, the results of the interaction diagram in fire situation shall be the same as the results

at room temperature. It was used as seed for the mesh generator: 15 mm for the concrete elements and 6 mm for the steel elements. The $M_y \times M_x$ interaction diagram of the column obtained by the USP web application (at room temperature) and by *Pisafo* (at room temperature and in fire situation) are illustrated in Figure 11. As expected, it is observed that the interaction diagrams at room temperature and in fire situation obtained by *Pisafo* are coincident and very close to the interaction diagram obtained by the USP web application, which allows to validate the algorithm implemented in *Pisafo*.



Figure 10

Modeling the cross section of the column in Pisafo

Figure 11

 $M_y \times M_x$ interaction diagrams obtained by (a) web application of USP and (b) Pisafo – at room temperature and in fire (the curves are overlapped because they are identical)

Table 5

Bending moment strength M_x and M_y (kN.cm) obtained by the application of USP and by Pisafo (using the diagrams proposed in ABNT NBR 6118:2014 [35])

Design strength	Application of USP	Pisafo	Error
M _x	1937.1	1952.62	0.8 %
My	1937.1	1952.65	0.8 %

Table 5 lists the numerical results of the bending moment strengths obtained by *Pisafo* using the diagrams proposed in ABNT NBR 6118:2014 [35], in comparison to the results obtained by the USP web application, showing that the results are very close.

3.4 $M_v \times M_v$ interaction diagram in fire situation

In order to evaluate the $M_y \times M_x$ interaction diagram in fire situation, a comparison was made between the numerical analysis developed by Cherem and Silva [16] and the results obtained by *Pisafo* for the same problem.

Cherem and Silva [16] analyzed a concrete column of 30×30 cm², using a concrete with f_{ck} of 30 MPa and 8 CA50 steel bars with a diameter of 10 mm and with a 30 mm of concrete cover. The fire analysis considered the standard fire curve of ISO 834-1:1999 [21] with a fire time of 90 minutes, a moisture content of 4 % for concrete and all faces exposed to fire (Figure 12). The cross section was also subjected to a compression axial load of 761.22 kN, corresponding to approximately 40 % of the room temperature-centered compressive strength, according to the authors. For the *Pisafo* mesh generation, the seed used had 15 mm for the concrete elements and 6 mm for the steel elements.

Due to the double symmetry of the section, Figure 13 illustrates a quarter of the $M_v \times M_x$ interaction diagram obtained by Cherem and

Figure 12

Results of the thermal analysis obtained by Pisafo for the column under study [16]

Figure 13

Comparison of the $M_y \times M_x$ interaction diagram obtained by Pisafo and Cherem and Silva [16], using the Advanced method and the Reduction factor (proposed by these authors)

Silva [16] and by *Pisafo*. The "Advanced method" [16] consists of obtaining the maximum strength of the section using the stress-strain curves proposed in ABNT NBR 15200:2012 by means of an algorithm that varies the strain in the center of gravity of the section and the curvatures around of the *x* and *y* axes, without limiting the maximum strain in the materials [36]. The "Reduction factor" [16] is an analytical method proposed by the authors, which consists of adjusting the $M_y \times M_x$ interaction diagram at room temperature for a reasonable approximation in a fire situation, without the need for thermal analysis.

It is observed in Figure 13 that, since *Pisafo* obtains the interaction diagram based on the strain profile [17, 35, 36], the interaction diagram obtained using the stress-strain diagrams of ABNT NBR 6118:2014 adapted for high temperatures is more conservative than the "Advanced method" [16], but still presenting an excellent adjustment (between -1.5 % and -10.3 %). When using the stress-strain diagrams of ABNT NBR 15200:2012, the interaction diagram obtained by *Pisafo* is even more conservative, as already observed in item 3.1, but close to the "Reduction factor" method [16], considered as reasonable by the authors.

4. Conclusions

In this study, a computational algorithm, called *Pisafo*, was developed to verify any sections of reinforced concrete subjected to unsymmetrical bending at room temperature and in fire situation. The algorithm was implemented in the Delphi development environment, whose programming language is Object Pascal. It was used the *EasyMesh* mesh generator, developed by MIT, and the *Thersys* thermal analysis algorithm, developed by Ribeiro [7]. The mechanical analysis consists of a stress integration algorithm, based on the strain profile of the cross section, given by the strain domains prescribed in ABNT NBR 6118:2014.

Pisafo allows the use of any fire curve in thermal analysis as well as various cross-sectional shapes by having a finite element mesh generator incorporated into the program. As results, *Pisafo* allows the elaboration of the interaction diagrams of the cross section: $M_y \times M_x$, $M_y \times N$ and $M_x \times N$.

For validation of the implemented algorithm, the axial load strength of "+" and "T" section columns obtained by *Pisafo* were compared with values presented in the technical literature, obtained in experiments. In addition, the bending moment strength of beams, as well as the $M_y \times M_x$ interaction diagrams, were also compared with results found in the technical literature, obtained with the use of recognized programs.

The results obtained by *Pisafo* in the analysis of columns subjected to the centered compression, when compared with the experimental results presented by Xu and Wu [2], were greater when using the diagrams proposed by ABNT NBR 6118:2014 modified for fire situation, reaching a difference of up to 28.5 %. When using the diagrams proposed by ABNT NBR 15200:2012, the strength values obtained by *Pisafo* were closer to the experimental results, with differences from -7.88 % to 5.06 %, depending on the type of cross section.

When comparing the results obtained by *Pisafo* for bending moment strength with those obtained by the web application developed at USP and by the software Super TempCalc, the errors are smaller. In relation to Super TempCalc, the differences reach -14.8 % when using the diagrams proposed by ABNT NBR 6118:2014 and ABNT NBR 15200:2012. Regarding the USP web application, for analysis at room temperature, the differences obtained using the diagrams proposed by ABNT NBR 6118:2014 are negligible, of the order of 0.80 %. However, the comparison of the interaction diagrams in fire situation obtained by *Pisafo* and in the work of Cherem and Silva [16], also with the diagrams proposed by ABNT NBR 6118:2014, lead to larger differences of the order of -1.5 % to -10.3 %.

It is believed that some factors contributed to this larger difference from the experimental results of Xu and Wu [2]. The first is because the real thermal properties of the concrete used in the tests are not exactly the same as those used by *Pisafo*, which uses values provided in the standards. Another factor that also contributes to this difference is the fact that the articles do not specify all the conditions of the test, such as the lack of data on the concrete cover or the moisture content of the concrete. In addition, it is emphasized the non-consideration of spalling in the computational analysis, which was also omitted by Xu and Wu [2] in the experimental results.

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